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P-15-03 KBS-3H. Initial data report for the Multi Purpose Test

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Abstract

The MultiPurpose Test (MPT), currently underway at the Äspö HRL, is a full-scale, demonstration of the KBS-3H reference design. The test is conducted without heating and includes the main KBS-3H components in a partial deposition drift configuration. The test installation was carried out according to the Drainage, Artificial Watering and air Evacuation (DAWE) procedure and the system behaviour is now being monitored through in-situ instrumentation. Dismantling and post-mortem analysis will be carried out at a later stage and the timing for this will be dependent on the measured data. MPT activities were started in 2011 as part of the KBS-3H project development (SKB 2012). The MPT is also affiliated with the LucoeX project and is partly funded by the European Commission.

This report presents measurement data from the in-situ instrumentation in the MPT during the period from December 7, 2013 to June 10, 2014. A total of 227 sensors were installed in the MPT. The pressure development is monitored as total pressure in the rock (27 sensors), bentonite blocks (13 sensors) and plug (3 sensors). Additionally pore pressure is measured in the rock (27 sensors) and bentonite blocks (23 sensors). The saturation process is followed by measuring the relative humidity (34 sensors), suction (32 sensors) and volumetric water content (13 sensors). The movements of the components are determined with extensometers (13 sensors) and inclinometers (6 sensors). The outflow through the plug is measured with a flowmeter outside the drift. The strains on the Supercontainer and the plug are measured with strain gauges (8 on the Supercontainer and 24 on the plug). A set of three gas pressure sensors were also installed.

Some of the sensors (33) were fitted to transmit their signals wirelessly. Seven transmitters and two receivers were installed for this purpose. Wireless signal transmission is a novel technique in nuclear waste management and its development is advanced in the MPT.

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1. INTRODUCTION

1.1 General

The common goal of SKB and Posiva is disposal of spent nuclear fuel from Swedish and Finnish nuclear power plants at depth in crystalline bedrock to ensure the safety of human beings and the environment for long periods of time. The method selected for the final repository is the KBS-3 method (Figure 1-1).

The reference design is KBS-3V employing vertical disposal of the waste canisters. Horizontal disposal of the canisters, KBS-3H, is a possible alternative which is being examined by the two organisations. SKB's and Posiva's current programmes for KBS-3 are detailed in SKB's RD&D Programme (SKB 2013) and in Posiva's TKS-2009 (Posiva 2010).

The Multi Purpose Test (MPT), currently underway at the Äspö HRL, is a full-scale, demonstration of the KBS-3H reference design carried out at -220 m. The test is conducted without heating and includes the main KBS-3H components in a partial deposition drift configuration (Figure 1-2). The test installation was carried out according to the Drainage, Artificial Watering and air Evacuation (DAWE, see chapter 1.2) procedure and the system behaviour is now being monitored through in-situ instrumentation. Dismantling and post-mortem analysis will be carried out at a later stage and the timing for this will be dependent on the measured data.

MPT activities were started in 2011 as part of the KBS-3H project development (SKB 2012). The MPT is also affiliated with the LucoeX project and is partly funded by the European Commission.



Figure 1-1. Schematic illustration of the KBS-3 method with its three barriers: the canister, the buffer and the rock. The vertical reference design is illustrated to the left and the horizontal alternative to the right.



Figure 1-2. The main KBS-3H components (Supercontainer, distance blocks and a compartment plug with transition zone) as configured in the MultiPurpose Test.

The initial conditions of the bentonite components used in the MPT are described in Table 1-1 (D4;01 Johanesson, 2014).

 Table 1-1. Initial conditions of the bentonite components.

Туре	Bulk density (kg/m ³)	Water content (%)	Degree of saturation (%)	Dry density (kg/m ³)
Distance/Transition blocks	2 071	20.6	92.4	1 718
SC ring blocks	2 106	11.0	65.6	1 898
SC end blocks	2 069	17.2	83.2	1 766
Pellet filling	1 000	21.0	32.8	826

1.2 Purpose and scope of this report

The objective of the MPT instrumentation is to study the buffer and filling component behavior during the early evolution of the system.Displacements, water content, pore and total pressure and swelling pressures at the rock and plug interfaces are measured.

This report presents the MPT instrumentation scheme and the associated set of initial data. This data set corresponds to the time period from the December 7, 2013 at 08:30 (initiation of DAWE procedures) to June 10, 2014 at 23:50. At 14:50 on December 7, 2013, increasing pressure due to the DAWE filling was observed and a maximum pressure of 235 kPa was reached at 15:15 after which the filling was stopped.

Practical details of the sensor and component installation procedures were reported previously (D4:03, Kronberg, 2015).

2 GEOMETRY AND COORDINATE SYSTEM

Given that the Supercontainer, distance and transition blocks are assembled in a facility above ground and installed as full components (packages), the sensor coordinates cannot be measured when installed in their final location. Instead, the position of the component is measured and the sensor coordinates calculated based on the measurement and the drawings. Adding to the complexity is that the sections are mirrored when comparing the above ground sensor installation with the below ground installed component, i.e., when looking at a sensor being installed to the left side on top of a bentonite block in the assembly facility that sensor will eventually be located to the right inside the drift (when looking from the outside and into the drift).

The MPT instrumentation was set up according to the coding system presented in chapter 2.1 with regard to the onsite Data Acquisition System (DAS.) From this standpoint the center of the plug collar is regarded as the zero position.

Data from the DAS is fed into SKB's SICADA database under a different coding system, which is described in chapter 2.2. For this purpose the drift end is considered to be position zero.

2.1 Data Acquisition System (DAS)

The frame of reference for the positions of the sensors in the MPT is indicated in Figure 2-1.



Figure 2-1. Frame of reference for MPT rock sensors (left) and frame of reference for MPT block sensors (right).

Three coordinates are used to identify specific positions in the drift:

- r = radial distance (mm) from the center of the sensor to the drift axis
- α = Clockwise angle (degrees) from the drift axis for the rock sensors and counterclockwise angle from the drift axis for the blocks sensors, relative to the vertical diameter of the drift
- d = distance (mm) from the origin of the test area (middle of the plug collar) towards the rear of the drift

This is a relative coordinate system referenced to the drift axis with origin in the plug. The absolute (topographic) coordinate system is given by the position of the drift in the Äspö HRL.

It should be noted that the total pressure sensors in bentonite blocks coded as 0990 do not follow the reference coordinate system described above. This discontinuity results from two of the total pressure sensors being moved to the plug after it was decided that more information about the pressure on the plug would be necessary. It was not possible to purchase new total pressure sensors because the delivery time did not fit with the schedule of the test.

Coding system

The sensors are identified according to the following code:

SS-DDDD-N where:

- SS refers to sensor type (see Table 2-1)
- DDDD refers to the position at which the sensor is installed (depth in cm from the center of the plug collar)
- N refers to sensor ordering and is only necessary in cases where several sensors of the same type are installed in the same zone and at the same depth. Sensor ordering starts by 1 and increases with the radius r. For the same radius, it increases with the value of angle α taking into account that the view is from the drift front towards the drift entrance.

Table 2-1. <i>C</i>	Codes for	types of	^e sensors.
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~ -	~
Code	Sensor
TP	Total pressure
PP	Pore pressure
WC	Water content capacitive
WP	Water content psychometric
WF	Water content soil moisture
DS	Displacement Supercontainer
DB	Displacement bentonite
DC	Displacement collar
IS	Inclination Supercontainer
IB	Inclination bentonite
SG	Strain Gauge
GP	Gas Pressure
FM	Flow Meter

2.2 SICADA

SICADA is SKB's main database, and the associated codification for the MPT sensors is as follows:

P XK DDD S N where:

- P refers to object point
- XK refers to KBS-3H experiment
- DDD refers to position at which the sensor is installed (depth in dm from the drift front)
- S refers to type of sensor (see Table 2.2)
- N refers to sensor ordering

Table 2-2. Codes for types of sensors in SICADA codification.

Code	Sensor
Т	Total pressure
U	Pore pressure
W	Water content
**	capacitive/psychrometric
D	Displacement
D	Supercontainer/bentonite
т	Inclination
1	Supercontainer/bentonite
S	Strain Gauge

The as-built design with the position (coordinates) of the sensors is presented in Appendix 1.

3 DESCRIPTION OF THE SENSORS

The different sensors that are placed in the blocks, pellets, Supercontainer, plug and rock are described in this chapter. The chapter also includes background information regarding sensor distribution and placement.

3.1 Sensor types

Total pressure measurement

Total pressure is the sum of the swelling pressure and the pore water pressure. It is measured with the following sensors:

- Geokon total pressure cells with vibrating wire transducers were installed in the rock wall at axial (to the drift, S1) and radial to the drift, S2, S4, S7, S8, S9 and S9⁺) measurement directions. Additionally, one of these sensors was placed in the axial direction at the S8/S9 block/block interface.
- Geokon total pressure cells with piezo resistive transducers (custom modified by ÅF, Sweden) were installed in bentonite block drift components. Specifically, these cells were placed in ring blocks and end blocks at block/canister interfaces, measuring radially to the drift axis for the former and along the drift axis for the latter, in distance blocks at the Supercontainer endplate/block interface measuring along the drift axis and at the pellet-filling/plug interface measuring along the drift axis.

Pore water pressure measurement

Pore water pressure is measured with the following sensors:

- Keller pore pressure piezo resistive sensors. These sensors are installed outside the test area and the pressure is transmitted through tubing connected to the borehole measurement locations. The tubing is equipped with porous stainless steel filters at the sampling ends. The boreholes are isolated with packer assemblies.
- Measurement Specialities 4 arm Wheatstone bridge. These sensors are installed in the blocks and pellets-filled zones.

Gas pressure measurement

Gas pressure is measured with the following sensors:

• Keller pore pressure sensors piezo resistive sensors. These sensors are installed outside the test area and the pressure is transmitted through tubing connected to the measurement location. The tubing has a porous stainless steel filter at the end.

The main aim for installing these sensors was for measuring the evolution of gas pressure if the DAWE was discarded. Essentially these sensors end up measuring the water pressure in the gap and should be changed by other sensors with higher range.

Water saturation measurement

The water saturation in the bentonite blocks is recorded by measuring the relative humidity in the pore system, which can be converted to total suction (negative water pressure). The following techniques and devices are used:

- Aitemin SHT75 v3 capacitive hygrometer. The measuring range is from 0 to 100% RH.
- Wescor type PST-55 thermocouple psychrometer with modification by Aitemin. The effective measuring range is from 95 to 99.6 % RH corresponding to suction between 54 to 6 916 kPa at 20°C. The psychrometer response is showed in Figure 3-1. Interpretation of the psychrometer signals requires parameter values in order to represent the different regions of the output trace (a-b-c-d-e) versus time. The signal corresponding to the c-d plateau is explicitly used for suction calculation. Therefore it is important to check the consistency of the input parameters and the times constants over long periods of signal collection.



Figure 3-1. General psychrometer response during the measurement process.

Volumetric water content measurement

The volumetric water is defined as V_{ω}/V_T (volume of water/total volume) and is measured in the MPT drift as follows:

Soil moisture sensors (ThetaProbe type ML2x, Delta-T Devices with custom modification by Aitemin) were installed in the bentonite blocks. The measuring range should cover all possible volumetric water contents. These sensors consist of a waterproof PVC housing, which contains the electronics, and, at the other end, four sharpened stainless steel rods that are inserted into the material to be analyzed. Given the swelling capacity of the bentonite buffer, the standard housing of the units was reinforced with a SS316L casing provided with a fitting for ¼" OD tubing (to protect the cable). Any remaining empty space in the casings was filled with resin. The output signal of these sensors is 0 to 1 V DC (Figure 3-2) for a range of soil dielectric constants, ε, from 1 to 32, which corresponds to a range of 0 to approximately 0.5 m³/m³ volumetric moisture content for generalized mineral soils. Soil-specific calibrations should be performed for these sensors.



Figure 3-2. *Relationship between ThetaProbe output and soil moisture content for generalized mineral and organic soils.*

The FDR sensors were placed in holes filled with powder with the same water content the block:

- Distance/transition blocks 21 %.
- Rings in Supercontainer, 11%
- Discs in Supercontainer, 17%

Strain measurement

Strains on the Supercontainer and plug face are measured with the following strain gauges:

- HBM 1-LY41-3/350 with a range of 0-50 000 μ m/m (plug face).
- HBM 1-XY101-3/350 with a range of 0-50 000 μ m/m (Supercontainer).

Displacement measurement

Displacements within the MPT drift are measured as follows:

- RDP LVDT sensors with a range ±25 mm were installed inside the drift to
 measuredisplacements of the Supercontainer with respect to the rock wall (section 4). In these
 cases, positive displacements indicate movement of the Supercontainer away from the rock.
 LVDT sensors were also installed in drift section 5 to measure the displacement of bentonite
 blocks with respect to the canister where positive displacements indicate movement away from
 the canister. Finally, in drift section 9, LVDT sensors were installed to measure the
 displacement between two blocks and where any positive increase indicates that the space
 between the blocks is increasing.
- RDP LVDT sensors with a range ±12.5 mm were installed outside the drift on the plug face to measure displacement of the plug along the drift axis.. Positive displacements indicate movement of the plug toward the drift.

Ideally these sensors would be installed measuring zero displacement but they were configured in a workshop and it is possible that they experienced some movement during emplacement of the blocks and Supercontainer.

Inclination measurement

Inclinations of the Supercontainer and bentonite blocks are measured as follows:

Measurement Specialities DPL series inclinometers with a range of \pm 5° were installed in . bentonite blocks in sections S2 and S7. The x-axis for the inclinometers corresponds to the longitudinal direction along the bottom of the drift and a positive angle response indicates an incline (counter clockwise rotation) away from the plug face. The y-axis for the inclinometers corresponds to the lateral direction of the drift and a positive response indicates an incline (clockwise rotation) away from the rock wall as drawn in Figure 2-1.

In section S4, the inclinometers were installed completely opposite to those in sections S2 and S7. As such, the y-axis for the inclinometers corresponds to the longitudinal direction along the bottom of the drift and a positive response indicates an incline (clockwise rotation) away from the rear of the drift and the x-axis corresponds to the lateral direction of the drift and a positive response indicates a decline (counter clockwise rotation) toward the rock wall as drawn in Figure 2-1.

3.2 Installed sensors

The locations of the measurement sections along the drift are presented in Figure 3-3 and the type and number of sensors are presented in Table 3-1.



Figure 3-3. Measurement section locations (DAS coding, with the plug as position 0).

Table 3.1 *Distribution of sensors by sections showing the distribution between those that are read by means of conventional cables (wired), wireless or tubing that transmits pressure.*

		SECTIONS											
Sensors	S1	S2	S3	S4	S5	S6	S 7	S8	S9	S9+	S10	OUT	тот
TP rock	5	4		2			4	4	2	6			27
TP plug											2+ <mark>1</mark>		3
TP buffer				4	4	4			1				13
PP rock short	1	4					4						9
PP rock borehole									18				18
PP buffer		3+ <mark>3</mark>		4	2+ <mark>3</mark>		1+ <mark>3</mark>				3+ <mark>3</mark>		23
WC		3+ <mark>3</mark>		4	2+ <mark>3</mark>		3+ <mark>3</mark>	4+ <mark>3</mark>	3+ <mark>3</mark>				34
WP		6		4	4		6	6	6				32
WF	1	2		2	2		2	2	2				13
DS				4	4								8
DB									2				2
DC												3	3
IS				2									2
IB		1					1		1+ <mark>1</mark>				4
GP	1					1					1		3
SG					8							24	32
FM												1	1
Total	8	27	0	26	32	5	27	19	39	6	10	28	227
Tubings	2	4	0	0	0	1	4	0	0	0	1	0	12
Wireless	0	6	0	0	6	0	6	5	6	0	4		33
Wired	8	21	0	26	26	5	21	14	33	6	6	28	194

3.3 Reasoning behind the distribution of sensors

This section introduces the reasoning behind the sections and their instrumentation.

Section S1

This section is in contact with the rock at the end of the drift. The instrumentation was installed to give the swelling pressure evolution in five points in contact with the rock. A pore pressure transducer was installed to give the drain effect inside the rock. A soil moisture sensor was installed to provide information about the evolution of the water content of the buffer (inner filling block).

A filter connected with a steel line was installed to be able to measure the remaining gas pressure at the upper part of the drift but also to measure the gas composition taking samples and analyzing in the laboratory. Due to DAWE procedure, this sensor was flooded from the beginning and no gas pressure was measured.

Sections S2 and S7

Both are hydraulically instrumented sections within the distance blocks at both sides of the Supercontainer. Four pore pressure transducers were installed to give the drain effect inside the rock walls and four total pressure cells were installed to track the swelling pressure evolution in contact with the rock. Within the buffer, the distribution of the sensors is radial in order to study the evolution of the saturation process from the rock to the inner part of the buffer. The distribution is in 4 different orientations for studying the effect of the saturation process in gravity sense and in perpendicular direction. The capacitive hygrometer and the psychrometers were installed to give the saturation process in all range (water potential which is related with the water content. The installation of pore pressure transducers at the same radius as in the rock was done to monitor the positive pressure when the buffer is saturated. An inclinometer was installed to inform about blocks tilting.

Section S3

This section only has a radio module to pass the Supercontainer.

Sections S4 & S4+

Located in the middle of the Supercontainer, the instrumentation of this section was installed to give the swelling pressure developed against the Supercontainer shell and the canister surface from the ring blocks. Capacitive hygrometers and psychrometers were distributed in two diameters to follow the evolution of the saturation process in the blocks from the rock to the inner part of the buffer. Two additional soil moisture sensors were installed to give the volumetric water content and four pore pressure transducers were installed to give the positive pressure when the buffer saturates. Two inclinometers were installed to inform about the package tilting (one close to the shell and another one close to the canister) and four extensometers were installed to monitor movements (S4+, in the next block because the lack of room in the previous one).

Sections S5 & S5-

This section, located close to the canister end, was instrumented for different purposes: first to follow the saturation process inside the Supercontainer thanks to the pore pressure transducers, the capacitive hygrometers, the psychrometers and the soil moisture sensors; second to track the swelling pressure developed against the canister by the end block bottom; third to measure the saturation process in the center of the end block bottom; and fourth to monitor canister movements regarding the Supercontainer shell (again located in the annex block due to the lack of room, S5-).

This section is also devoted to monitor the mechanical behavior of the Supercontainer. 8 strain gauges were glued on to the Supercontainer shell to detect failures when the strains change suddenly.

Section S6

The instrumentation of S6 was installed to give the swelling pressure developed against the Supercontainer from the distance blocks. A filter connected with a steel line was installed to be able to measure the gas pressure due the possible corrosion of the Supercontainer but also to measure the gas composition taking samples and analyzing in the laboratory. Due to the DAWE procedure, this sensor was flooded from the beginning.

Section S7

See S2, these have the same configuration and objectives.

Section S8

This section was installed to follow the saturation process within the transition blocks by means of suction and water content instrumentation and total pressure cells installed at the rock walls. Two additional soil moisture sensors were installed to give the volumetric water content.

Section S9

This section is the closest to the pellets filling, so it will be possible to see if there are any differences with respect to the other sections and to assess the effect of the pellets on block saturation. In the pellet zone, a total pressure sensor is installed for assessing the swelling pressure developed by the pellets onto the blocks.

Soil moisture sensors and suction instruments were installed in four perpendicular radii to study the saturation process on the opposite side respect to the pellets in order to avoid quick saturation of the sensors during the DAWE. The swelling pressure development against the rock is measured too. Two sensors were installed in the buffer to monitor possible movements; two inclinometers were also installed.

Pore pressure sensors were installed in the three boreholes in this drift section to provide information about groundwater flow.

Section S9+

Section S9+ is located 0.9 m from the plug and was added in order to install six total pressure cells that could not fit in sections S9 & S10 for practical reasons.

Section S10

This section is mainly for studying the swelling pressure development against the plug. The instrumentation has a double purpose. On the one hand it provides information about the stresses against the plug (total pressure in some locations) and on the other it provides information to compare with the swelling pressure developed in the Supercontainer side (section 4 and the other sections from 4 till plug) for studying the development of friction between the bentonite and the rock. In order to be able to measure the effective pressure, pore pressure sensors were installed. There was a gas pressure sensor in this section but it was flooded from the beginning due to the DAWE procedure.

Section OUT

This is not strictly a section. It comprises all the transducers installed outside the sealed test section.

As with the Supercontainer shell, 16 strain gauges were installed on the cap to monitor the stress state. A temperature sensor was installed to measure for temperature compensation in the strain gauges measures. Three displacement transducers were installed to inform about plug movements and for comparing the behavior of this system with the plug tested before (SKB 2012).

A flowmeter system was installed to be used for measuring the water leakage from the plug.

In the following chapters (4 - 6), outer sensor positions refer to those sensors located at the interface between the MPT drift boundaries (i.e., rock wall or plug) and drift components whereas inner sensor positions refer to those sensors located within MPT drift components.

4 DISTANCE BLOCKS

The sensors in the distance blocks are located in drift sections S-1, S-2, S-6 and S-7 (Figure 3-1).

4.1 Inner sensor positions

The location of the inner sensors and other information is presented in Tables 4-1 (section 1), 4-2 (section 2), 4-3 (section 6) and 4-4 (section 7).

Table 4-1. Numbering and position of inner distance block sensors in drift section 1.

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1904.721	7253.178	-217.881	WF	PXK003WF1	WF-1867	ML2x377/048	Delta-T
2	1904.870	7253.179	-216.447	GP	PXK004GP1	GP-1856	GP 1892-1	Keller

Table 4-2. Numbering and position of inner distance block sensors in drift section 2.

	Coordi	nate system	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1906.208	7253.179	-216.564	WF2	PXK017WF2	WF-1722-2	WF 1722-2	Delta-T
2	1906.208	7252.972	-216.592	WP4	PXK017WP4	WP-1722-4	WP 1722-4	Wescor
3	1906.207	7253.386	-216.591	WC5	PXK017WC5	WC-1722-5	WC 1722-5	Aitemin
4	1906.082	7253.179	-216.809	IB1	PXK016IB1	IB-1722	IB 1722-1	Measurement Specialities
5	1906.203	7252.613	-216.798	PP3	PXK017PP3	PP-1722-3	wireless	Measurement Specialities
6	1906.202	7253.745	-216.798	PP2	PXK017PP2	PP-1722-2	wireless	Measurement Specialities
7	1906.195	7253.114	-217.123	WP1	PXK017WP1	WP-1722-1	WP 1722-1	Wescor
8	1906.195	7253.244	-217.123	WC2	PXK017WC2	WC-1722-2	wireless	Aitemin
9	1906.191	7252.380	-217.314	WP5	PXK017WP5	WP-1722-5	WP 11722-5	Wescor
10	1906.189	7252.381	-217.414	WC6	PXK017WC6	WC-1722-6	WC 1722-6	Aitemin
11	1905.940	7253.842	-217.303	WSU	transmitter	WSU-S2	wireless	Aitemin
12	1906.189	7253.978	-217.314	WP3	PXK017WP3	WP-1722-3	WP 1722-3	Wescor
13	1906.187	7253.978	-217.414	WC4	PXK017WC4	WC-1722-4	wireless	Aitemin
14	1906.184	7253.054	-217.581	WP2	PXK017WP2	WP-1722-2	WP 1722-2	Aitemin
15	1906.184	7253.304	-217.581	WC1	PXK017WC1	WC-1722-1	wireless	Wescor
16	1906.173	7252.779	-218.057	PP4	PXK017PP4	PP-1722-4	PP 1722-4	Measurement Specialities
17	1906.171	7252.972	-218.137	WP6	PXK017WP6	WP-1722-6	WP 1722-6	Wescor
18	1906.170	7253.179	-218.163	WF1	PXK017WF1	WF-1722-1	WF 1722-1	Delta-T
19	1906.170	7253.386	-218.137	WC3	PXK017WC3	WC-1722-3	WC 1722-3	Aitemin
20	1906.172	7253.580	-218.057	PP1	PXK017PP1	PP-1722-1	wireless	Measurement Specialities

Table 4-3. Numbering and position of inner distance block sensors in drift section 6.

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1913.463	7252.635	-217.644	TP3	РХК090ТР3	TP-0990-2	TP 0990-3	Geokon /ÅF
2	1913.461	7253.745	-217.644	TP5	РХК090ТР5	TP-0990-4	TP 0990-5	Geokon / ÅF
3	1913.449	7253.190	-218.199	TP2	РХК090ТР2	TP-0990-1	TP 0990-2	Geokon / ÅF
4	1913.704	7253.190	-216.787	GP1	PXK092GP1	GP-0967	GP 0967-1	Keller
5	1913.462	7253.190	-217.088	TP4	РХК092ТР4	TP-0990-3	TP 0990-4	Geokon / ÅF

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1915.653	7252.628	-217.158	PP3	PXK112PP3	PP-0820-3	wireless	Measurement Specialities
2	1915.657	7252.986	-216.952	WP4	PXK112WP4	WP-0820-4	WP 0820-4	Wescor
3	1915.658	7253.193	-216.924	WF2	PXK112WF2	WF-0820-2	WF 0820-2	Delta-T
4	1915.657	7253.401	-216.951	WC5	PXK112WC5	WC-0820-5	WC 0820-5	Aitemin
5	1915.651	7253.759	-217.158	PP2	PXK112PP2	PP-0820-2	wireless	Measurement Specialities
6	1915.645	7253.128	-217.483	WP1	PXK112WP1	WP-0820-1	WP 0820-1	Wescor
7	1915.644	7253.258	-217.483	WC2	PXK112WC2	WC-0820-2	wireless	Aitemin
8	1915.641	7252.395	-217.673	WP5	PXK112WP5	WP-0820-5	WP 0820-5	Wescor
9	1915.639	7252.395	-217.773	WC6	PXK112WC6	WC-0820-6	WC 0820-6	Aitemin
10	1915.634	7253.068	-217.940	WP2	PXK112WP2	WP-0820-2	WP 0820-2	Wescor
11	1915.633	7253.319	-217.940	WC1	PXK112WC1	WC-0820-1	wireless	Aitemin
12	1915.639	7253.992	-217.673	WP3	PXK112WP3	WP-0820-3	WP 0820-3	Wescor
13	1915.636	7253.992	-217.773	WC4	PXK112WC4	WC-0820-4	wireless	Aitemin
14	1915.623	7252.793	-218.416	PP4	PXK112PP4	PP-0820-4	PP 0820-4	Measurement Specialities
15	1915.621	7252.986	-218.496	WP6	PXK112WP6	WP-0820-6	WP 0820-6	Wescor
16	1915.620	7253.193	-218.522	WF1	PXK112WF1	WF-0820-1	WF 0820-1	Delta-T
17	1915.620	7253.401	-218.496	WC3	PXK112WC3	WC-0820-3	WC 0820-3	Aitemin
18	1915.622	7253.594	-218.416	PP1	PXK112PP1	PP-0820-1	wireless	Measurement Specialities
19	1915.532	7253.193	-217.175	IB1	PXK109IB1	IB-0820	IB 0820-1	Measurement Specialities
20	1915.449	7253.856	-217.664	WSUS7	transmmiter	WSU-S7	wireless	Aitemin

Table 4-4. Numbering and position of inner distance block sensors in drift section 7.

4.2 Inner sensor results and comments

4.2.1 Relative humidity

The relative humidity sensors in the peripheral positions of the blocks have measured increases in the relative humidity as expected. No changes have been measured with the sensors in more inward locations of the blocks. The results are presented in Figures 4-1 and 4-2.



- - WC-1722-1 - - WC-1722-2 - WC-1722-3 - - WC-1722-4 - WC-1722-5 - WC-1722-6



Figure 4-1. Response of capacitive hygrometer sensors at inner distance block positions (in the bentonite block) in drift section S-2. A total of six such sensors were installed in this section (bottomright inset; WC-1 corresponds to WC-1772-1, etc.). The sensors in more peripheral positions recorded increases in relative humidity from the beginning of the test whereas the sensors closer to the center showed little to no increase in relative humidity. Dashed lines correspond to wireless sensors (WC-1, WC-2 and WC-4). Signal was being received from these sensors until just over 100 days into the test after which they have not transmitted as intended.



-- WC-0820-1 -- WC-0820-2 -- WC-0820-3 -- WC-0820-4 --- WC-0820-5 --- WC-0820-6



Figure 4-2. Response of capacitive hygrometer sensors at inner distance block positions (in the bentonite block) in drift section S-7. A total of six such sensors were installed in this section (bottomright inset; WC-1 corresponds to WC-0820-1, etc.). The sensors in more peripheral positions recorded increases in relative humidity from the beginning of the test whereas the sensors closer to the center showed little to no increase in relative humidity. Sensor WC-3 showed an early spike in relative humidity perhaps due to the initial water filling of the gap. Dashed lines correspond to wireless sensors (WC-1, WC-2 and WC-4). Signal was received from these sensors only from around 90 until just over 100 days into the test, before and after that they have not transmitted as intended.

It seems that the response pattern is similar in both sections, showing that the sensor at the right side (WC-6 in both sections) measured an increase in relative humidity before the other sensors. The reason could be related with a higher gap (more water available) on the right side during the emplacement of the blocks or due to a sudden movement/rotation just after the water filling. Such an asymmetric wetting process is evident in the psychrometer results as well.

4.2.2 Suction

In-range signals from the psychrometer sensors correspond only to suction established at 95% relative humidity. For temperatures between 5 °C and 15 °C, the suction at 95% relative humidity should be between 6.6 and 6.8 MPa based on the psychometric law. The results are presented in Figures 4-3 to 4-6.



Figure 4-3. Response of psychrometers at inner distance block positions (in the bentonite block) in drift section S-2. A total of six such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-1722-1, etc.). Sensors WP-3, WP-5 and WP-6 in more peripheral locations have reached in-range suction limits (see also Figure 4-4). The signals for sensors closer to the center have not yet started to approach in-range limits.



Figure 4-4. *Decay in psychrometer signal for sensors WP-3, WP-5 and WP-6 in inner distance block positions in drift section 2 after reaching in-range suction limits.*



Figure 4-5. Response of psychrometers at inner distance block positions (in the bentonite block) in drift section S-7. A total of six such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-0820-1, etc.). Sensors WP-3, WP-5 and WP-6 in more peripheral locations reached in-range suction limits after 85 to 125 days (see also Figure 4-6). The signals for sensors closer to the center have not yet started to approach in-range limits.



Figure 4-6. *Decay in psychrometer signal for sensors WP-3, WP-5 and WP-6 in inner distance block positions in drift section 7 after reaching in-range suction limits.*

4.2.3 Pore pressure

Pore pressures in the blocks were measured with pore pressure sensors (Figures 4-7 and 4-8). The pressure in the gap was measured (Figure 4-9) with a gas pressure sensor. In most cases, the pore pressure sensors in the blocks did not measure any increase in pore pressure. This observation may be due to the low hydraulic conductivity of the bentonite. The measurement results are presented in Figures 4-7 to 4-9.

Similarly, the BRIE test, also conducted in the Äspö HRL, was instrumented with pore pressure sensors and pressure increases were not observed (Fransson et al., 2014). Other examples indicating delays in the development of measurable pore pressures in bentonite blocks include the FEBEX test (Enresa, 2000) and the ESDRED test both performed at the Grimsel Test Site (Switzerland).



Figure 4-7. Response of pore pressure sensors at inner distance block positions (in the bentonite block) in drift section S-2. A total of four such sensors were installed in this section (bottom-right inset; PP-1 corresponds to PP-1722-1, etc.). Dashed lines correspond to wireless sensors (PP-1, PP-2 and PP-3). Signal was being received from these sensors until just over 100 days into the test. Sensor PP-4 was starting to show increasing signal after 140 days.



Figure 4-8. Response of pore pressure sensors at inner distance block positions (in the bentonite block) in drift section S-7. A total of four such sensors were installed in this section (bottom-right inset; PP-1 corresponds to PP-0820-1, etc.). Dashed lines correspond to wireless sensors (PP-1, PP-2 and PP-3). Signal was received from these sensors only from around 90 until just over 100 days into the test. Sensor PP-4 has displayed an unreasonably large signal since the beginning of the test and may be malfunctioning.



Figure 4-9. Response of gas pressure sensor in drift section S-1 (bottom-right inset). The full sensor range is 250 kPa and it was installed for the purposes of measuring the gas pressure during the water filling if the DAWE procedure was not followed. The sensor was flooded and essentially measured water pressure. After less than 10 days it reached the maximum capacity. This sensor should be changed to a higher range pore pressure sensor which is possible because the gas pressure sensors are located outside of the drift.

4.2.4 Water content

Volumetric water content was measured with soil moisture sensors (Figures 4-10 to 4-12).



Figure 4-10. Response of soil moisture sensor at inner distance block position (in the bentonite block) in drift section S-1. The sensor measured a decrease in signal until a constant value was reached after 100 days. This behavior could be related with expansion/fracturing of the bentonite which could lead to new voids in the vicinity of the measuring rods and lower signal. This block is in the rear of the drift and may be more prone to suffer expansion/breaking.



Figure 4-11. Response of soil moisture sensors at inner distance block positions (in the bentonite block) in drift section S-2. A total of two such sensors were installed in this section (bottom-right inset; WF-1 corresponds to WF-1772-1 and WF-2 corresponds to WF-1772-2). Increasing signals were measured by both sensors over the course of the test.



Figure 4-12. Response of soil moisture sensors at inner distance block positions (in the bentonite block) in drift section S-7. A total of two such sensors were installed in this section (bottom-right inset; WF-1 corresponds to WF-0820-1 and WF-2 corresponds to WF-0820-2). Sensor WF-2 measured an increasing signal over most of the test but sensor WF-1 displayed a constant signal throughout which indicates it may be malfunctioning. The behavior of WF-2 at the beginning of the test is similar to WF-1867 (Figure 4-10) but the signal decreases less and an increase of the signal is also observed. The explanation for this behavior could be the same: expansion/fracturing of the bentonite but to a lesser extent due to higher confinement of the blocks.

4.2.5 Inclination

Results from the inclinometer sensors are presented in Figures 4-13 and 4-14. The reference inclination is the one after the emplacement.



Figure 4-13. *Response of the inclinometer sensor at inner distance block position (in the bentonite block) in drift section S-2. A sudden change in inclination at 3 days to a constant value was measured suggesting a sudden rotation of the block towards the pilot borehole possibly due to block swelling.*



Figure 4-14. *Response of inclinometer sensor at inner distance block position (in the bentonite block) in drift section S-7. One sensor was installed in this block (bottom-right inset) and only inclination along the x-axis was measured. Signal was recorded from this sensor after 54 days. The signal trend appears to indicate a slow inclination towards the plug.*

4.3 Outer sensor positions

The location of the outer sensors and other information is presented in Tables 4-4 (section 1), 4-5 (section 2) and 4-6 (section 7).

Table 4-4. Numbering and position of outer distance block sensors in drift section 1.

	Coordinate system ÄSPÖ 96							
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
4	1904.504	7252.779	-216.885	PP-1	PXK000PP1	PP-1877-1	PP-1877-1	Keller
6	1904.509	7253.186	-216.724	TP-2	PXK000TP2	TP-1877-2	TP-1877-2	Geokon
5	1904.483	7253.754	-217.303	TP-3	PXK000TP3	TP-1877-3	TP-1877-3	Geokon
3	1904.460	7253.329	-217.857	TP-4	PXK000TP4	TP-1877-4	TP-1877-4	Geokon
1	1904.465	7252.656	-217.820	TP-5	PXK000TP5	TP-1877-5	TP-1877-5	Geokon
2	1904.483	7252.601	-217.302	TP-1	PXK000TP1	TP-1877-1	TP-1877-1	Geokon

Table 4-5. Numbering and position of outer distance block sensors in drift section 2.

	Coordinate system ÄSPÖ 96							
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
10	1905.955	7252.519	-216.707	PP-6	PXK015PP6	PP-1732-6	PP-1732-6	Keller
12	1905.954	7252.950	-218.239	PP-5	PXK015PP5	PP-1732-5	PP-1732-5	Keller
14	1905.951	7253.424	-218.236	PP-8	PXK015PP8	PP-1732-8	PP-1732-8	Keller
8	1905.950	7253.849	-216.708	PP-7	PXK015PP7	PP-1732-7	PP-1732-7	Keller
11	1905.954	7252.261	-217.359	TP-2	PXK015TP2	TP-1732-2	TP-1732-2	Geokon
13	1905.957	7253.180	-218.268	TP-1	PXK015TP1	TP-1732-1	TP-1732-1	Geokon
9	1905.946	7254.106	-217.365	TP-4	PXK015TP4	TP-1732-4	TP-1732-4	Geokon
7	1905.950	7253.186	-216.425	TP-3	PXK015TP3	TP-1732-3	TP-1732-3	Geokon

Table 4-6. Numbering and position of outer distance block sensors in drift section 7.

Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
17	1915.376	7252.533	-217.076	PP-6	PXK109PP6	PP-0788-6	PP-0788-6	Keller
19	1915.372	7252.956	-218.613	PP-5	PXK109PP5	PP-0788-5	PP-0788-5	Keller
21	1915.381	7253.433	-218.610	PP-8	PXK109PP8	PP-0788-8	PP-0788-8	Keller
23	1915.373	7253.853	-217.075	PP-7	PXK109PP7	PP-0788-7	PP-0788-7	Keller
18	1915.376	7252.270	-217.712	TP-2	PXK109TP2	TP-0788-2	TP-0788-2	Geokon
20	1915.387	7253.201	-218.642	TP-1	PXK109TP1	TP-0788-1	TP-0788-1	Geokon
24	1915.387	7254.114	-217.715	TP-4	PXK109TP4	TP-0788-4	TP-0788-4	Geokon
22	1915.376	7253.198	-216.796	TP-3	PXK109TP3	TP-0788-3	TP-0788-3	Geokon

4.4 Outer sensor results and comments

4.4.1 Total pressure

Total pressure is measured in sections 1, 2 and 7 (see Figures 4-15 to 4-17).



Figure 4-15. Response of total pressure sensors at outer distance block positions (measuring axial pressures at the rock wall surface) in drift section S-1 (bottom-right inset). A total of five such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-1892-1, etc.). The sensors generally show increasing pressure. The signal from sensor TP-1892-5 appears to level off after 100 days. The negative values are due to changes in the baseline signals. This effect is very common because of the installation and rearrangement of the oil inside the cell. It is negligible for these sensors.



Figure 4-16. Response of total pressure sensors at outer distance block positions (measuring radial pressures at the rock wall surface) in drift section S-2 (bottom-right inset). A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-1747-1, etc.). The sensors generally show increasing pressure with a leveling off after 100 days. The sensors also respond similarly to TP-1895-2 (see Figure 4-15), indicating that the bentonite is still not in contact with the rock or the swelling pressure is still low and the pressure measured is mainly water pressure.


Figure 4-17. Response of total pressure sensors at outer distance block positions (measuring radial pressures at the rock wall surface) in drift section 7 (bottom-right inset). A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-0803-1, etc.). The sensors generally show increasing pressure with a leveling off after 100 days. The sensors also respond similarly to TP-1895-2 (see Figure 4-15), indicating that the bentonite is still not in contact with the rock or the swelling pressure is still low and the pressure measured is mainly water pressure.

4.4.2 **Pore pressure**

Pore pressure is measured in drift sections 1, 2 and 7 (see Figures 4-18 to 4-20).



Figure 4-18. *Response of pore pressure sensor in drift section 1 (bottom-right inset). The sensor appears to be malfunctioning or the tubing is not fully air purged.*



Figure 4-19. Response of pore pressure sensors in drift section S-2 (bottom-right inset, PP-5 corresponds to TP-1747-5, etc.). Sensor PP-6 showed an increase in pressure through 55 days and decreasing pressure thereafter. This behavior could be due to gas compression, especially taking into account that the PP-6 is in upper position, so it has more risk of having air inside. Sensor PP-8 displayed similar behavior to that observed for the total pressure sensors (see Figure 4-16), i.e., increases in pressure until approximately 100 days flowed by a levelling off. Sensors PP-5 and PP-7 may be malfunctioning or the tubing is plugged.



Figure 4-20. Response of pore pressure sensors in drift section S-7 (bottom-right inset, TP-5 corresponds to TP-0803-5, etc.). Sensor PP-5 showed a sudden increase in pressure starting at 105 days. Sensor PP-8 displayed similar behavior to that observed for the total pressure sensors (see Figure 4-17), i.e., increases in pressure until approximately 100 days flowed by a levelling off. Sensor PP-6 shows unexpectedly low pressures. This behavior could be due to gas compression, so the pipes should be purged. Sensor PP-7 appears to be malfunctioning or the tubing is plugged.

5 TRANSITION ZONE

5.1 Inner sensor positions

The location of the inner sensors and other information is presented in tables 5-1 (drift section 8, transition blocks), 5-2 (drift section) and 5-3 (drift section 10). All sections are presented in Figure 3-1.

Table 5-1. Numbering and position of inner transition zone sensors in drift section 8 (transition blocks).

	Coordi	nate system	n ÄSPÖ 96					
Point No.	Easting [m]	Northing [m]	Point Elevation	Drawing label	Sensor code in SICADA	Sensor code in SCADA	Assembly tag label	Manufacturer
			[m]					
1	1919.068	7252.991	-217.082	WP4	PXK146WP4	WP-0480-4	WP0480-4	Wescor
2	1919.069	7253.198	-217.054	WF2	PXK146WF2	WF-0480-2	WF0480-2	Delta-T
3	1919.068	7253.406	-217.081	WC6	PXK146WC6	WC-0480-6	WC0480-6	Aitemin
4	1919.062	7253.062	-217.346	WP1	PXK146WP1	WP-0480-1	WP0480-1	Wescor
5	1919.062	7253.336	-217.346	WC3	PXK146WC3	WC-0480-3	WC0480-3	Aitemin
6	1919.052	7252.400	-217.803	WP5	PXK146WP5	WP-0480-5	WP0480-5	Wescor
7	1919.050	7252.400	-217.903	WC7	PXK146WC7	WC-0480-7	WC 0480-7	Aitemin
8	1919.050	7253.198	-217.853	WC1	PXK146WC1	WC-0480-1	WC0480-1	Aitemin
9	1919.040	7253.082	-218.287	WP2	PXK146WP2	WP-0480-2	WP0480-2	Wescor
10	1919.039	7253.315	-218.287	WC2	PXK146WC2	WC-0480-2	WC0480-2	Aitemin
11	1919.032	7252.991	-218.626	WP6	PXK146WP6	WP-0480-6	WP0480-6	Wescor
12	1919.031	7253.198	-218.652	WF1	PXK146WF1	WF-0480-1	WF0480-1	Delta-T
13	1919.031	7253.406	-218.626	WC4	PXK146WC4	WC-0480-4	WC0480-4	Aitemin
14	1919.050	7253.997	-217.803	WP3	PXK146WP3	WP-0480-3	WP0480-3	Wescor
15	1919.047	7253.997	-217.903	WC5	PXK146WC5	WC-0480-5	WC0480-5	Aitemin
16	1918.860	7253.861	-217.794	WSUS8	transmmiter	WSU-S8	wireless	Aitemin

Table 5-2. Numbering and position of inner transition zone sensors in drift section 9 (transition blocks).

,	Coordi	nate system	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1920.398	7253.200	-217.360	IB2	PXK159IB2	IB-0286-2	IB0311-2	Measurement Specialities
2	1920.499	7253.264	-218.148	WC1	PXK160WC1	WC-0286-1	wireless	Aitemin
3	1920.372	7253.200	-218.450	IB1	PXK159IB1	IB-0286-1	wireless	Measurement Specialities
4	1920.739	7253.201	-217.921	TP1	PXK163TP1	TP-0292-3	DRIFT	Geokon
5	1920.524	7253.200	-217.112	WF2	PXK160WF2	WF-0286-2	WF0286-2	Delta-T
6	1920.486	7253.408	-218.681	WC3	PXK160WC3	WC-0286-3	WC0286-3	Aitemin
7	1920.523	7252.993	-217.137	WP4	PXK160WP4	WP-0286-4	WP0286-4	Wescor
8	1920.523	7253.408	-217.136	WC5	PXK160WC5	WC-0286-5	WC0286-5	Aitemin
9	1920.507	7252.402	-217.858	WP5	PXK160WP5	WP-0286-5	WP0286-5	Wescor
10	1920.505	7252.402	-217.958	WC6	PXK160WC6	WC-0286-6	WC0286-6	Aitemin
11	1920.511	7253.136	-217.668	WP1	PXK160WP1	WP-0286-1	WP0286-1	Wescor
12	1920.510	7253.265	-217.669	WC2	PXK160WC2	WC-0286-2	wireless	Aitemin
13	1920.505	7253.999	-217.858	WP3	PXK160WP3	WP-0286-3	WP0286-3	Wescor
14	1920.502	7253.999	-217.958	WC4	PXK160WC4	WC-0286-4	wireless	Aitemin
15	1920.315	7253.863	-217.849	WSUS9	transmmiter	WSU-S9	wireless	Aitemin
16	1920.742	7252.746	-217.651	DB2	PXK163DB2	DB-0286-2	wireless	RDP
17	1920.723	7253.655	-218.176	DB1	PXK163DB1	DB-0286-1	wireless	RDP
18	1920.499	7253.136	-218.146	WP2	PXK160WP2	WP-0286-2	WP0286-2	Wescor
19	1920.487	7252.993	-218.681	WP6	PXK160WP6	WP-0286-6	WP0286-6	Wescor
20	1920.486	7253.200	-218.707	WF1	PXK160WF1	WF-0286-1	WF0286-1	Delta-T

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1922.700	7252.311	-217.995	PP5	PXK182PP5	PP-0029- 5	PP-0000-5	Measurement Specialities
2	1922.697	7254.097	-217.995	PP4	PXK182PP4	PP-0029-4	PP-0000-4	Measurement Specialities
3	1922.698	7253.204	-217.995	TP1	PXK182TP1	TP-0029-1	wireless	Geokon / ÅF
4	1922.698	7253.205	-217.925	PP1	PXK182PP1	PP-0029-1	wireless	Measurement Specialities
5	1922.935	7253.205	-217.347	PP3	PXK185PP3	PP-0029-3	wireless	Measurement Specialities
6	1922.903	7253.205	-218.667	PP2	PXK185PP2	PP-0029-2	wireless	Measurement Specialities
7	1922.719	7253.250	-217.099	GP1	PXK182GP1	GP-0029	GP-0000-1	Keller
8	1922.719	7253.158	-217.099	PP6	PXK182PP6	PP-0029-6	PP-0000-6	Measurement Specialities
9	1922.642	7253.467	-217.934	WSUS10	transmmiter	WSU-S10	wireless	Aitemin
10	1923.892	7253.207	-217.531	DC1	PXK200DC1	DC-100-1	Aitemin	RDP
11	1923.875	7253.207	-218.031	DC2	PXK200DC2	DC-100-2	Aitemin	RDP
12	1923.867	7253.207	-218.531	DC3	PXK200DC3	DC-100-3	Aitemin	RDP
13	1922.849	7253.205	-218.569	TP-2	PXK182TP2	TP-0029-2	close to PP2	Geokon / ÅF
14	1922.902	7253.205	-217.404	TP-3	PXK182TP3	TP-0029-3	close to PP3	Geokon / ÅF

Table 5-3. Numbering and position of inner transition zone sensors in drift section 10 (pellets).

5.2 Inner sensor results and comments

5.2.1 Relative humidity

The relative humidity sensors in the peripheral positions of the blocks have measured increases in the relative humidity as expected. No changes have been measured with the sensors in more inward locations of the blocks. The results are presented in Figures 5-1 and 5-2.



Figure 5-1. Response of capacitive hygrometer sensors at inner transition zone positions (in the bentonite block) in drift section S-8. A total of seven such sensors were installed in this section (bottom-right inset; WC-1 corresponds to WC-0480-1, etc.) and signal is being recorded from four of them. Dashed lines correspond to wireless sensors (WC-1, WC-3 and WC-5). Signal was lost from these sensors a few hours into the test. The signal from sensor WC-6 was lost at close to 60 days.



Figure 5-2. Response of capacitive hygrometer sensors at inner transition zone positions (in the bentonite block) in drift section S-9. A total of six such sensors were installed in this section (bottomright inset; WC-1 corresponds to WC-0286-1, etc.). Dashed lines correspond to wireless sensors (WC-1, WC-2 and WC-4). Signal was received from sensors WC-1 and WC-4 only from 50 to 60 days. No signal was received from sensor WC-2. The signal from sensor WC-6 was lost at close to 60 days.

5.2.2 Suction

In-range signals from the psychrometer sensors correspond only to suction established at 95% relative humidity. For temperatures between 5 °C and 15 °C, the suction at 95% relative humidity should be between 6.6 and 6.8 MPa. The results are presented in Figures 5-3 to 5-5.



Figure 5-3. Response of psychrometers at inner transition zone positions (in the bentonite block) in drift section S-8. A total of six such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-0480-1, etc.). Sensors WP-5 and WP-6 in more peripheral locations have reached in-range suction limits (see also Figure 5-4). The signals for sensors closer to the center have not yet started to approach in-range limits.



Figure 5-4. Decay in psychrometer signal for sensors WP-5 and WP-6 in inner transition zone positions in drift section 8 after reaching in-range suction limits.



Figure 5-5. Response of psychrometers at inner transition zone positions (in the bentonite block) in drift section S-9. A total of six such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-0286-1, etc.). Sensors WP-4 and WP-6 are approaching in-range suction limits while the other sensors have not yet started to approach in-range limits. Sensor WP-2 appears to be malfunctioning. It should also be taken into account that these sensors are close to the pellet filling (on the opposite side of the block in contact with the pellets, i.e., 485 mm) and the resulting signals may be influenced by any block/pellet interactions.

5.2.3 **Pore pressure**

The pore pressure sensors are located at the pellet-filling/plug interface in drift section 10 (Figures 5-6 and 5-7).



Figure 5-6. Response of pore pressure sensors at inner transition zone positions in the pellet-filled zone in drift section 10. A total of six such sensors were installed in this section (bottom-right inset; PP-1 corresponds to PP-0029-1, etc.). Signal was not recorded from sensors PP-4, PP-5 and PP-6 until approximately 50 days. No signal has been received from wireless sensors PP-1, PP-2 or PP-3 since 11.12.2013. Although it is expected that the pellet zone is filled with water, only sensor PP-4 shows a clear increase in pressure and levelling off but sensors PP-5 and PP-6 do not. If the water filled the pellet zone at a spatially localized inflow point, inhomogeneous wetting, swelling and sealing may result (see e.g., Hoffman, 2005).



Figure 5-7. Response of gas pressure sensor at inner transition zone position in the pellet-filled zone in drift section 10 (bottom-right inset). The full sensor range is 250 kPa and it was installed for the purposes of measuring the gas pressure during the water filling if the DAWE procedure was not followed. The sensor was flooded and essentially measured water pressure. This sensor should be changed to a higher range pore pressure sensor which is possible because the gas pressure sensors are located outside of the drift. This sensor is close to sensor PP-6 (see Figure 5-6).

5.2.4 Water content

Volumetric water content was measured with soil moisture sensors (Figure 5-8).



Figure 5-8. Response of soil moisture sensors at inner transition zone positions (in the bentonite block) in drift section S-9. A total of two such sensors were installed in this section (bottom-right inset; WF-1 corresponds to WF-0286-1 and WF-2 corresponds to WF-0286-2). An increasing signal was measured by sensor WF-1 whereas sensor WF-2 displayed a lower, relatively constant signal.

5.2.5 Inclination

Results from the inclinometer sensors are presented in Figure 5-9.



Figure 5-9. Response of the inclinometer sensors at inner transition zone positions (in the bentonite block) in drift section S-9. A total of two such sensors were installed in this section (IB-0286-1 and IB-0286-2). Sensor IB-1 is a wireless sensor and no signal has been received from this sensor. Sensor IB-2 showed a sudden change in both the positive x- and y-directions after 3 days to constant values. This behavior is similar to IB 1722-X (Figure 4-13).

5.2.6 **Displacement**

Two wireless, displacement sensors (DB-0286-1 and DB-0286-2) were installed in drift section 9. Signal was received from these sensors only from 29 January to 5 February 2013.

5.2.7 Total pressure

Total pressure sensors were installed at the pellet-plug interface to the inner face of the plug (Figure 5-10).



Figure 5-10. Response of total pressure sensors at the pellet-plug interface in drift section S-10. The pressure is measured orthogonal to plug. A total of three such sensors were installed in this section (TP-0029-1, TP-0029-2 and TP-0286-3). Sensor TP-1 is a wireless sensor and no signal has been received from this sensor. Little to no pressure has been detected by sensors TP-2 and TP-3.

5.3 Outer sensor positions

The location of the outer sensors and other information is presented in tables 5-4 and 5-5 (drift sections 8 and 9, transition blocks) and 5-6 (drift section 9+, pellets). This section also contains information regarding the strain gauges on the plug face (Table 5-7).

Table 5-4. Numbering and position of outer transition zone sensors in drift section 8 (transition blocks).

Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
25	1918.782	7253.204	-216.928	TP-3	PXK143TP3	TP-0449-3	TP-0449-3	Geokon
26	1918.778	7252.300	-217.620	TP-2	PXK143TP2	TP-0449-2	TP-0449-2	Geokon
27	1918.774	7253.203	-218.771	TP-1	PXK143TP1	TP-0449-1	TP-0449-1	Geokon
28	1918.774	7254.085	-217.615	TP-4	PXK143TP4	TP-0449-4	TP-0449-4	Geokon

Table 5-5. Numbering and position of outer transition zone sensors in drift section 9 (transition blocks).

Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
29	1920.494	7252.961	-218.804	TP-2	PXK161TP2	TP-0277-2	TP-0277-2	Geokon
30	1920.498	7253.212	-216.991	TP-1	PXK161TP1	TP-0277-1	TP-0277-1	Geokon

Table 5-6. Numbering and position of outer transition zone sensors in drift section 9+ (pellets).

		U	<u> </u>					1 /
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
31	1922.365	7253.203	-217.058	TP-4	PXK178TP4	TP-0000-4	TP-0000-4	Geokon
32	1922.316	7252.301	-217.739	TP-1	PXK178TP1	TP-0150-1	TP-0150-1	Geokon
33	1922.314	7252.303	-218.227	TP-3	PXK178TP3	TP-0000-3	TP-0000-3	Geokon
34	1922.302	7253.192	-218.901	TP-2	PXK178TP2	TP-0000-2	TP-0000-2	Geokon
35	1922.324	7254.082	-218.233	TP-5	PXK178TP5	TP-0000-5	TP-0000-5	Geokon
36	1922.363	7254.081	-217.739	TP-2	PXK179TP2	TP-0150-2	TP-0150-2	Geokon

	Coordi	inate system	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1920.505	7251.669	-217.045	PP-2	PXK16PP2	PP-0292-2	PP-0292-2	Keller
2	1920.547	7250.325	-216.256	PP-5	PXK16PP5	PP-0292-5	PP-0292-5	Keller
3	1920.572	7249.549	-215.800	PP-8	PXK16PP8	PP-0292-8	PP-0292-8	Keller
4	1920.600	7248.635	-215.264	PP-11	PXK16PP11	PP-0292-11	PP-0292-11	Keller
5	1920.625	7247.851	-214.803	PP-14	PXK16PP14	PP-0292-14	PP-0292-14	Keller
6	1920.742	7244.135	-212.622	PP-17	PXK16PP17	PP-0292-17	PP-0292-17	Keller
7	1920.448	7253.208	-219.700	PP-1	PXK16PP1	PP-0292-1	PP-0292-1	Keller
8	1920.384	7253.206	-221.259	PP-4	PXK16PP4	PP-0292-4	PP-0292-4	Keller
9	1920.347	7253.205	-222.158	PP-7	PXK16PP7	PP-0292-7	PP-0292-7	Keller
10	1920.262	7253.202	-224.226	PP-10	PXK16PP10	PP-0292-10	PP-0292-10	Keller
11	1920.226	7253.201	-225.125	PP-13	PXK16PP13	PP-0292-13	PP-0292-13	Keller
12	1920.090	7253.196	-228.433	PP-16	PXK16PP16	PP-0292-16	PP-0292-16	Keller
13	1920.523	7254.695	-217.053	PP-3	PXK16PP3	PP-0292-3	PP-0292-3	Keller
14	1920.557	7255.607	-216.515	PP-6	PXK16PP6	PP-0292-6	PP-0292-6	Keller
15	1920.586	7256.382	-216.058	PP-9	PXK16PP9	PP-0292-9	PP-0292-9	Keller
16	1920.643	7257.906	-215.159	PP-12	PXK16PP12	PP-0292-12	PP-0292-12	Keller
17	1920.672	7258.680	-214.701	PP-15	PXK16PP15	PP-0292-15	PP-0292-15	Keller
18	1920.815	7262.476	-212.461	PP-18	PXK16PP18	PP-0292-18	PP-0292-18	Keller

 Table 5-7. Numbering and position of sensors inside rock in drift section 9.

5.4 Outer sensor results and comments

5.4.1 Total pressure

Total pressure measurements are presented in Figures 5-11 to 5-13.



Figure 5-11. Response of total pressure sensors at outer transition zone positions, at the rock wall surface, in drift section 8. A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-0464-1, etc.). The sensors all show similar behavior of increasing pressure leveling off after 100 days.



Figure 5-12. Response of total pressure sensors at outer transition zone positions (at the rock wall surface) in drift section 9. A total of two such sensors were installed in this section (bottom-right inset; TP-2 corresponds to TP-0292-2 and TP-3 to TP-0292-3). TP-1 corresponds to a sensor installed in the buffer block. Similar to the total pressure sensors in drift section 8 (see Figure 5-11), sensor TP-2 shows increasing pressure with a leveling off after 100 days. It is likely this sensor is measuring pore pressure. Sensor TP-3 displays continuously increasing pressure; it is possible that more significant swelling pressure has developed at this position and/or the block has shifted to a resting position on the bottom of the drift.



Figure 5-13. Response of total pressure sensors at outer transition zone positions (at the rock wall surface) in drift section 9+. A total of six such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-0089-1, etc.). The sensors all show similar behavior of increasing pressure leveling off after 100 days and resemble that observed for sensor PP-0029-4 (see Figure 5-6) in the pellet-filled zone in drift section 10. The initially lower values from sensor TP-4 may be due to a shallow collapse of the pellets during the DAWE phase. This sensor also displayed signal instability between 130-145 days and a jump in pressure at 180 days probably due to material rearrangement, very common in pellets (Mayor et al., 2005a, 2005b).

5.4.2 **Pore pressure**

Pore pressure measurements in the three boreholes drilled into the rock wall in drift section 9 are presented in Figures 5-14 to 5-16. The packer system generated peak pressures on December 10 and 27, 2013. These peaks were registered by the total pressure sensors.



Figure 5-14. Response of pore pressure sensors at outer transition zone positions in borehole 1 (KA1619A05 in Äspö reference) in drift section 9. A total of six such sensors were installed in this borehole (bottom-right inset; PP-1 corresponds to PP-0292-1, etc.).



Figure 5-15. Response of pore pressure sensors at outer transition zone positions in borehole 2 (KA1619A06 in Äspö reference) in drift section 9. A total of six such sensors were installed in this borehole (bottom-right inset; PP-2 corresponds to PP-0292-2, etc.).



Figure 5-16. Response of pore pressure sensors at outer transition zone positions in borehole 3 (KA1620A02 in Äspö reference) in drift section 9. A total of six such sensors were installed in this borehole (bottom-right inset; PP-3 corresponds to PP-0292-3, etc.).

5.4.3 **Displacements in plug**

Signals from displacement sensors on the plug face are presented in Figure 5-17.



Figure 5-17. *Response of displacement sensors on the plug face in drift section 10 (bottom-right inset). Overall the measured displacements are quite small and near the limit of detection of the sensors. The observed jumps in displacements are likely due to work being performed at or near the plug face.*

5.4.4 Strains in plug





Figure 5-18. Response of vertical strain gauges on the plug face in drift section 10 (bottom-right inset). Increasing strains are observed over the course of the test at every position indicating the development of pressure behind the plug. Strain gauge SG-P10V displays anomalous behavior relative to the others. Strain gauges SG-P5V and SG-P12V have failed.



Figure 5-19. Response of horizontal strain gauges on the plug face in drift section 10 (bottom-right inset). Increasing strains are observed over the course of the test at every position indicating the development of pressure behind the plug. Strain gauge SG-P11H displays a jump in measured strain at approximately 60 days.

6 SUPERCONTAINER

6.1 Inner sensor positions

The location of the inner sensors and other information is presented in Tables 6-1 (drift section 4), 6-1 (drift section 2) and 6-3 (drift section 7). This section also contains information regarding the strain gauges on the Supercontainer in drift section 3 (Table 6-4). All sections are presented in Figure 3-1.

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1910.864	7252.987	-216.798	WP2	PXK061WP2	WP-1299-2	WP-1293-2	Wescor
2	1910.861	7252.599	-216.954	PP3	PXK061PP3	PP-1299-3	PP-1293-3	Measurement Specialities
3	1910.848	7252.418	-217.491	WP3	PXK061WP3	WP-1299-3	WP-1293-3	Wescor
4	1910.846	7252.419	-217.591	WC4	PXK061WC4	WC-1299-4	WC-1293-4	Aitemin
5	1910.833	7252.599	-218.128	PP4	PXK061PP4	PP-1299-4	PP-1293-4	Measurement Specialities
6	1910.828	7252.987	-218.284	WP4	PXK061WP4	WP-1299-4	WP-1293-4	Wescor
7	1910.827	7253.386	-218.284	WC1	PXK061WC1	WC-1299-1	WC-1293-1	Aitemin
8	1910.831	7253.773	-218.128	PP1	PXK061PP1	PP-1299-1	PP-1293-1	Measurement Specialities
9	1910.843	7253.955	-217.591	WC2	PXK061WC2	WC-1299-2	WC-1293-2	Aitemin
10	1910.846	7253.955	-217.491	WP1	PXK061WP1	WP-1299-1	WP-1293-1	Wescor
11	1910.859	7253.186	-217.006	TP2	PXK061TP2	TP-1299-2	TP-1299-2	Geokon /ÅF
12	1910.864	7253.186	-216.771	WF2	PXK061WF2	WF-1299-2	WF-1293-2	Delta-T
13	1910.867	7253.187	-216.678	TP4	PXK061TP4	TP-1244-4	TP-1299-4	Geokon /ÅF
14	1910.845	7253.722	-217.541	TP1	PXK061TP1	TP-1299-1	TP-1299-1	Geokon /ÅF
15	1910.827	7253.186	-218.311	WF1	PXK061WF1	WF-1299-1	WF-1293-1	Delta-T
16	1910.847	7252.651	-217.541	TP3	PXK061TP3	TP-1299-3	TP-1299-3	Geokon /ÅF
17	1910.863	7253.386	-216.798	WC3	PXK061WC3	WC-1299-3	WC-1293-3	Aitemin
18	1910.859	7253.774	-216.954	PP2	PXK061PP2	PP-1299-2	PP-1293-2	Measurement Specialities

Table 6-1. Numbering and position of inner Supercontainer sensors in drift section 4.

Table 6-2. Numbering and position of inner Supercontainer displacement and inclinometer sensors indrift section 4.

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1911.329	7253.187	-217.007	IS2	PXK072IS2	IS-1252-2	no data	Measurement Specialities
2	1911.060	7253.187	-218.433	DS1	PXK069DS1	DS-1275-1	DS-1492-1	RDP
3	1911.079	7254.069	-217.554	DS2	PXK069DS2	DS-1275-2	DS-1492-2	RDP
4	1911.082	7252.305	-217.553	DS4	PXK069DS4	DS-1275-4	DS-1492-4	RDP
5	1911.295	7253.187	-218.407	IS1	PXK072IS1	IS-1252-1	no data	Measurement Specialities
6	1911.102	7253.187	-216.671	DS3	PXK069DS3	DS-1275-3	DS-1492-3	RDP

	Coordi	nate systen	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1913.289	7252.991	-216.889	WP2	PXK0087WP2	WP-1008-2	WP 1008-2	Wescor
2	1913.289	7253.190	-216.863	WF2	PXK0087WF2	WF-1008-2	WF 1008-2	Delta-T
3	1913.288	7253.390	-216.890	WC4	PXK0087WC4	WC-1008-4	wireless	Aitemin
4	1913.291	7253.190	-216.804	PP4	PXK0087PP4	PP-1008-4	wireless	Measurement Specialities
5	1913.272	7252.361	-217.633	PP5	PXK0087PP5	PP-1008-5	PP 1008-5	Measurement Specialities
6	1913.273	7252.422	-217.583	WP3	PXK0087WP3	WP-1008-3	WP 1008-3	Wescor
7	1913.271	7252.422	-217.683	WC5	PXK0087WC5	WC-1008-5	WC 1008-5	Aitemin
8	1913.253	7252.991	-218.376	WP4	PXK0087WP4	WP-1008-4	WP1008-4	Wescor
9	1913.251	7253.190	-218.462	PP2	PXK0087PP2	PP-1008-2	PP 1008-2	Measurement Specialities
10	1913.252	7253.190	-218.403	WF1	PXK0087WF1	WF-1008-1	WF 1008-1	Delta-T
11	1913.252	7253.389	-218.376	WC2	PXK0087WC2	WC-1008-2	WC 1008-2	Aitemin
12	1913.271	7253.959	-217.583	WP1	PXK0087WP1	WP-1008-1	WP 1008-1	Wescor
13	1913.269	7254.020	-217.633	PP3	PXK0087PP3	PP-1008-3	wireless	Measurement Specialities
14	1913.268	7253.959	-217.683	WC3	PXK0087WC3	WC-1008-3	wireless	Aitemin
15	1913.272	7253.190	-217.583	PP1	PXK0087PP1	PP-1008-1	wireless	Measurement Specialities
16	1913.270	7253.190	-217.683	WC1	PXK0087WC1	WC-1008-1	wireless	Aitemin
17	1913.040	7253.190	-217.377	TP3	PXK085TP3	TP-1033-3	TP 1033-3	Geokon / ÅF
18	1913.034	7252.940	-217.627	TP2	PXK085TP2	TP-1033-2	TP 1033-2	Geokon / ÅF
19	1913.028	7253.190	-217.877	TP1	PXK085TP1	TP-1033-1	TP 1033-1	Geokon / ÅF
20	1913.033	7253.440	-217.627	TP4	PXK085TP4	TP-1033-4	TP 1033-4	Geokon / ÅF
21	1913.081	7253.853	-217.573	WSU	transmmiter	WSU-S4	wireless	Aitemin

Table 6-3. Numbering and position of inner Supercontainer sensors in drift section 5.

Table 6-4. Numbering and position of inner Supercontainer displacement sensors in drift section 5.

	Coordi	nate system	n ÄSPÖ 96					
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label	
			[m]					
1	1912.546	7252.813	-217.233	DS3	PXK081DS3	DS-1082-3	DS-0977-3	RDP
2	1912.544	7253.565	-217.233	DS2	PXK081DS2	DS-1082-2	DS-0977-2	RDP
3	1912.526	7253.565	-217.985	DS4	PXK081DS4	DS-1082-4	DS-0977-4	RDP
4	1912.527	7252.806	-217.992	DS1	PXK081DS1	DS-1082-1	DS-0977-1	RDP

6.2 Inner sensor results and comments

6.2.1 Relative humidity

Signals from sensors measuring relative humidity evolution are presented in Figures 6-1 and 6-2.



Figure 6-1. Response of capacitive hygrometer sensors at inner Supercontainer positions (in the bentonite block) in drift section 4. A total of four such sensors were installed in this section (bottom-right inset; WC-1 corresponds to WC-1299-1, etc.). Generally, the sensors indicate increasing relative humidity levels over the course of the test. The reason for the initial drop in signal for sensor WC-1299-3 is unknown but it could be related with block cracking/expansion. Initial signals correspond to 52% RH rather than 84% RH (see Figures 4-1, 4-2, 5-1 and 5-2) because the buffer blocks (inside the Supercontainer) are dryer than the transition zone blocks or distance blocks.



Figure 6-2. Response of capacitive hygrometer sensors at inner Supercontainer positions (in the bentonite block) in drift section 5. A total of five such sensors were installed in this section (bottomright inset; WC-1 corresponds to WC-1008-1, etc.). Sensors WC-1, WC-2, WC-3 and WC-5 showed a spike in relative humidity during the DAWE phase of the test probably due to a gap between the final disc block and the ring and canister. This gap was sealed quickly due to the bentonite swelling. Sensor WC-1 is between the the block and the canister inside the block. Signal was no longer available form sensor WC-5 after 5 days. Sensor WC-2 reached full saturation after approximately 60 days. Signal was no longer received from the wireless sensors (WC-1, WC-3 and WC-4) after just over 100 days.

6.2.2 Suction

In-range signals from the psychrometer sensors correspond only to suction established at 95% relative humidity. For temperatures between 5 °C and 15 °C, the suction at 95% relative humidity should be between 6.6 and 6.8 MPa. The results are presented in Figures 6-3 to 6-5.



Figure 6-3. Response of psychrometer sensors at inner Supercontainer positions (in the bentonite block) in drift section 4. A total of four such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-1299-1, etc.). The signals for these sensors have not yet started to approach in-range limits, i.e., the block is not sufficiently saturated.



Figure 6-4. Response of psychrometers at inner Supercontainer positions (in the bentonite block) in drift section S-5. A total of four such sensors were installed in this section (bottom-right inset; WP-1 corresponds to WP-1008-1, etc.). The sensors were in range at the early stage of the test probably due to a gap between the final disc block and the ring and canister. This gap was sealed quickly due to the bentonite swelling. It is possible to see the same behavior in capacitive hygrometers in Figure 6-2. All of the sensors have reached in-range suction limits (see also Figure 6-5).



Figure 6-5. Decay in psychrometer signal for sensors WP-1, WP-2, WP-3 and WP-4 in inner Supercontainer positions in drift section 5 after reaching in-range suction limits. The sensors WP-2 and WP-5 were somewhat noisy which could be related to chamber contamination. The bentonite salts moved with the water towards the sensor and the signal is affected due to the operating principle of the sensor (drying/wetting cycles).

6.2.3 Pore pressure

Pore pressures in the Supercontainer blocks was measured with pore pressure sensors (Figures 6-6 and 6-7). The pressure in the gap was measured (Figure 6-8) with a gas pressure sensor.



Figure 6-6. Response of pore pressure sensors at inner Supercontainer positions (in the bentonite block) in drift section 4. A total of four such sensors were installed in this section (bottom-right inset; PP-1 corresponds to PP-1299-1, etc.). Signal was not available from sensor PP-3.



Figure 6-7. Response of pore pressure sensors at inner Supercontainer positions (in the bentonite block) in drift section 5. A total of five such sensors were installed in this section (bottom-right inset; PP-1 corresponds to PP-1008-1, etc.). Dashed lines correspond to wireless sensors (PP-1, PP-3 and PP-4). Signal was received from these sensors only between 70 to just over 100 days into the test. Signal was not available form sensor PP-2. Sensor PP-5 probably is in contact with the gap filled with water due to block cracks.


Figure 6-8. Response of gas pressure sensor in drift section 6 (bottom-right inset). The full sensor range is 250 kPa and it was installed for the purposes of measuring the gas pressure during the water filling if the DAWE procedure was not followed. The sensor was flooded during the water filling and essentially measured water pressure. After approximately 20 days it reached the maximum capacity. This sensor should be changed to a higher range pore pressure sensor which is possible because the gas pressure sensors are located outside of the drift.

6.2.4 Water content

Volumetric water content was measured with soil moisture sensors (Figures 6-9 and 6-10).



Figure 6-9. Response of soil moisture sensors at inner Supercontainer positions (in the bentonite block) in drift section 7. A total of two such sensors were installed in this section (bottom-right inset; WF-1 corresponds to WF-1299-1 and WF-2 corresponds to WF-1299-2). Sensor WF-2 measured an increasing signal over the course of the test but sensor WF-1 may have malfunctioned as it displayed a constant signal until almost 60 days after which signal was no longer available.



Figure 6-10. Response of soil moisture sensors at inner Supercontainer positions (in the bentonite block) in drift section 5. A total of two such sensors were installed in this section (bottom-right inset; WF-1 corresponds to WF-1008-1 and WF-2 corresponds to WF-1008-2). After an initial drop, sensor WF-1 measured an increasing signal over most of the test but sensor WF-2 displayed a relatively constant signal throughout which indicates it may be malfunctioning.

6.2.5 Inclination

Results from the inclinometer sensors are presented in Figure 6-11.



Figure 6-11. Response of inclinometers at inner Supercontainer positions (in the bentonite block) in drift section 4. A total of two such sensors were installed in this section (bottom-right inset; IS-1 corresponds to IS-1252-1 and IS-2 corresponds to IS-1252-2). Signal is being recorded only from sensor IS-1 along the x-axis. This sensor suggests that the block showed first a sudden rotation to the left (counterclockwise) after 3 days which gradually reversed over 100 to 180 days.

6.2.6 **Displacement**

Results from the displacement sensors are presented in Figures 6-12 and 6-13.



Figure 6-12. Response of displacement sensors at inner Supercontainer positions in drift section 4. These sensors measure the displacements between the Supercontainer shell and the drift wall. A total of four such sensors were installed in this section (bottom-right inset; DS-1 corresponds to DS-1275-1, etc.). Sensors DS-2 and DS-4 both measured positive displacements from 30 to 50 days onward. Sensor DS-3 did not register any change in displacement. No signal was recorded from sensor DS-1. These sensors are fixed to the Supercontainer and measure displacement with respect to the rock wall. Sensors DS-2 and DS-4 both show positive displacement which may indicate that the Supercontainer moved up or down. The interpretation of these signals is complex because they can be influenced by a variety of different movements.



Figure 6-13. Response of displacement sensors at inner Supercontainer positions in drift section 5. These sensors measure the displacement between the bentonite block and the canister. A total of four such sensors were installed in this section (bottom-right inset; DS-1 corresponds to DS-1082-1, etc.). Sensor DS-3 measured a positive displacement (movement away from the canister) over the course of the test. Sensor DS-1 showed a smaller, negative displacement (movement toward the canister). Essentially no change in displacement was observed with Sensor DS-4. No signal was recorded from sensor DS-2. These signals are difficult to interpret. The block may be expanding more in the upper right area.

6.2.7 Total pressure

Results from the total pressure sensors are presented in Figures 6-14 to 6-16.



Figure 6-14. Response of total pressure sensors at inner Supercontainer positions (in the bentonite block at the ring block/canister interface measuring radially to the drift axis) in drift section 4. A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-1299-1, etc.). Only background noise was thus far recorded by these sensors over the course of the test.



Figure 6-14. Response of total pressure sensors at inner Supercontainer positions (in the bentonite block at the end block/canister interface measuring along the drift axis) in drift section 5.A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-1033-1, etc.). Only background noise was thus far recorded by these sensors over the course of the test.



Figure 6-15. Response of total pressure sensors at inner Supercontainer positions (in the bentonite block at the Supercontainer endplate/distance block interface measuring along the drift axis) in drift section 6.A total of four such sensors were installed in this section (bottom-right inset; TP-1 corresponds to TP-0990-1, etc.). Only background noise was thus far recorded by these sensors over the course of the test.

6.2.8 Strains

The results from the strain gauge measurements on the Supercontainer surface are presented in Figure 6-16.



Figure 6-16. Response of strain gauges to circumferential strains on the Supercontainer surface in drift section 6 (bottom-right inset). Signal was recorded from only two of the strain gauges (SG-SP1 and SG-SP2) beyond a few days into the test. These gauges have not measured any significant strains and show similar behavior from approximately 50 days onward.

6.3 Outer sensor positions

The location of the sensors and other information is presented in Table 6-6.

Table 6-6. Numbering and position of outer Supercontainer sensors in drift section 4.

	Coordi	nate systen	n ÄSPÖ 96						
Point No.	Easting	Northing	Point	Drawing	Sensor code	Sensor code in	Assembly	Manufacturer	
	[m]	[m]	Elevation	label	in SICADA	SCADA	tag label		
			[m]						
15	1910.661	7254.110	-217.551	TP-8	PXK062TP8	TP-1259-8	TP-1259-8	Geokon	
16	1910.670	7252.268	-217.547	TP-7	PXK062TP7	TP-1259-7	TP-1259-7	Geokon	

6.4 Outer sensor results and comments

Only total pressure measurements are made in outer Supercontainer positions (Figure 6-17).



Figure 6-17. Response of total pressure sensors at outer Supercontainer positions (at the rock wall surface) in drift section 4. A total of two such sensors were installed in this section (bottom-right inset; TP-5 corresponds to TP-1275-5 and TP-6 corresponds to TP-1275-6). The sensors generally show increasing pressure which appears to level off after 100 days.

7 ASSESSMENT OF THE INITIAL STATE OF THE TEST

7.1 Total pressure

The total pressure measured at the drift walls is similar to the pore pressure measured by some of the pore pressure sensors in the rock and by sensors located in blocks at the gap interface (see Figures 7-1 and 7-2). It is only in drift section 1 that higher pressures (possibly including some component of swelling pressure against the rock wall) are measured. The existence of limited swelling pressure against the plug could be inferred from the strain gauges measurements.



Figure 7-1. Response of total pressure sensors at outer Supercontainer positions at the rock wall surface in the MPT drift (TP-1747-3 in S-2, TP-1275-6 in S-4, TP-0803-2 in S-7, TP-0464-3 in S-8 and TP-0292-2 in S-9). All of the total pressure sensors are in the highest parts of the tunnel except TP-1275-6, which is located in the gable end of the tunnel. PP-1747-8 is a pore pressure sensor in the rock located in S-2 and PP-1008-5 is a pore pressure sensor in the block located in S-5. All of the sensors display similar evolution measuring pressures between approximately 400 to 1000 kPa at the end of the measurement period.



Figure 7-2. Response of total pressure sensors in transition zone positions in the pellet-filling (S-9+) and the pore pressure measured in S-10 with sensor PP-0029-4. The tendency was the same for all sensors although the values were different. All of the sensors display similar evolution measuring pressures between approximately 400 to 600 kPa at the end of the measurement period.

The total pressure measured in the drift walls is strongly correlated with pore pressure.

Inflow into the 95 meter drift has been monitored since it was excavated in 2005. Initially, the inflow was approximately 12 l/min but by 2007 it had naturally come down to around 5 l/min. In 2007-2008 the five positions of highest inflows into the drift were grouted. As a result the inflow was reduced to approximately 0.4 l/min (Eriksson and Lindström, 2008). By 2011 the inflow had naturally decreased to roughly 0.25 l/min.

In order to monitor the inflow into the MPT drift, a set of wooden weirs were installed along its length (Figure 7-3). The weirs were placed where the rock conditions allowed it, but they match up quite well with the component lengths. Inflow data is presented in Table 7-1.



Figure 7-3. Wooden weir used to enable monitoring of groundwater inflow into the MPT drift.

A summary of the inflow data is provided below:

Full MPT section two months prior to installation~32 l/day (22.2 ml/min)Supercontainer section in 2012~19 l/day (13.2 ml/min)Inner distance block section in 2012~8 l/day (5.6 ml/min)Outer distance block, transition block and pellets section in 2012~3 l/day (2.1 ml/min)

It can be noted that the inflow into the MPT drift is well below 0.1 l/min which is the KBS-3H limit for emplacement of a Supercontainer.

Table 7-1. Inflow into the MPT drift during 2011-2013; possible outliers are marked in red. *Measurements were limited in 2013 due to development work on the deposition machine.*

Date	drift end-	drit end-	drift end-	dift end-	drift end-	drift end-	drift end-	Date	dift end -
	4,07 m	9,07 m	11,17 m	17,87 m	19,27 m	34,47 m	94,47 m		18,47 m
	(l/min)	(l/min)	(I/min)	(I/min)	(I/min)	(//min)	(I/min)*		(l/min)
2011-09-20	0,0060	0.0140		0,0240		0, 1480	0,2200		
2011-09-21	0,0060	0,0230	0,0290	0,0220		0, 1460	0,2200		
2011-09-22	0,0065	0,0215	0,0215	0,0225		0, 1470	0,2100		
2011-10-06	0,0062	0,0182	0,0212	0,0217		0, 1560	0,2100	2013-00-23	0,0226
2011-10-20	0,0058	0.0200	0,0202	0,0215		0, 1500	0,2130	2013-08-26	0,0220
2011-11-08	0,0060	0,0200	0,0205	0,0205		0,1540	0,1980	2013-09-09	0,0216
2011-11-21	0,0055	0,0195	0,0205	0,0210		0, 1360	0,1930	2013-09-10	0,0236
2011-12-06	0,0060	0,0194	0,0197	0,0205		0, 1330	0,1930	2013-09-12	0,0230
2012-01-10	0,0060	0,0195	0,0195	0,0205		0, 1350	0,1930	2013-09-16	0,0232
2012-05-22	0,0056	0.0190	0,0190	0,0205		0, 1700		2013-09-18	0,0224
2012-06-07	0,0053	0,0186	0,0190	0,0193		0,1330	0,1830	2013-09-19	0,0224
2012-06-28	0,0056	0,0190	0,0190	0,0198	0,0202	0, 1330	0,1900	2013-09-23	0,0224
2012-07-18	0,0055	0,0190	0,0190	0,0200	0,0260	0,1300	0,1830	2013-09-25	0,0200
2012-09-27	0,0050	0,0162			0,0162	<mark>0, 1280</mark>		2013-09-30	0,0280
2012-10-17	0,0050	0,0180	0,0180	0,0180	0,0200	0, 1260	0,1800	2013-10-04	0,0228

*There is a natrual tendency for lower inflows over time

Additional inflow measurements along the test section of the drift have been ongoing since 2011 (see Figure 7-4).



Figure 7-4. Inflows in different sections of the drift since 2011.

7.2 Borehole pore pressures

Pore pressure measurements were made in three boreholes drilled into the rock wall in drift section 9. Stable measurements were observed in boreholes 1 and 3 after 40 days but not until 100 days in borehole 2. Pore pressure after 185 days is presented in Figure 7-5.



Figure 7-5. Borehole pore pressures as a function of distance to drift after 185 days. The sensors in boreholes 1 and 2 displayed expected responses; decreasing pressures closer to the drift. The sensors installed near to the drift showed lower pore pressure than sensors inside the drift (PP-1747-8 and 1299-1) possibly due to the initial water filling. The behavior of the sensors in borehole 3 is unexpected and it is possible that the packers have not properly sealed the sensor cavities. Another possibility is that borehole 3 intersects other fractures and the cavities are connected to each other.

7.3 Saturation

The saturation process can be followed with the capacitive hygrometers (Figures 7-6 and 7-7). These sensors are able to measure the full range of humidity from 0-100% but above 95% the errors are too large and another sensor is needed for measuring at the highest relative humidities. Psychrometers were installed in order to cover the full range.



Figure 7-6. Evolution of the relative humidity in different sections along the bottom of the drift. 1722 corresponds to section 2, 1008 to section 4, 1299 to section 5, 0820 to section 7, 0480 to section 8 and 0286 to section 9.



Figure 7-7. Early evolution of the relative humidity in different sections along the bottom of the drift. 1722 corresponds to section 2, 1008 to section 4, 1299 to section 5, 0820 to section 7, 0480 to section 8 and 0286 to section 9. Sensors WC-1008-2 and WC-0820-3 showed increases in relative humidity due to DAWE which abated, presumably, due to the filling water being drawn away from the sensor positions.

The initial relative humidity measurements depend on the initial water content of the blocks. Different blocks have different initial water contents as follows:

- Distance blocks and transition blocks: $21 \pm 1 \%$
- Supercontainer end blocks: $17 \pm 1 \%$
- Supercontainer ring-shaped blocks: $11 \pm 1 \%$

As such, the initial relative humidity values measured with the capacitive hygrometers differ as a function of their position.

- Distance blocks and transition blocks: In drift section 2, the wireless hygrometers measured 83.5% and the wired hygrometers measured 84.5%. The wireless hygrometers are located in the inner part of the block. In drift section 7, the hygrometers measured between 81.9 and 83.5% independent of whether they were wired or wireless. In drift section 9, only the wired sensors provided signals at the beginning of the test which were between 84.3 and 83.5%.
- Supercontainer end blocks: In drift section 5 the wired sensors measured 73.9% but the wireless sensors measured 83% (see Figure 7-8).
- Supercontainer ring-shaped blocks (section 4): In drift section 4 all of the sensors are wired and measured relative humidities between 52.2 and 52.8%.



Figure 7-8. Early evolution of the relative humidity in drift section 5. Sensor WC-4 showed an initial value under 83%. There was a general increase in relative humidity due to DAWE. Drift section 5 has a complex tubing system and it is possible that the water flowed directly to the sensors and was later drawn away.

The psychrometers started to be in range at different times. It depends more of the position in the block than the section.

The pore pressure sensors need to have access to free water in order to make measurements, therefore (long) delays between the moment the block reaches 100% relative humidity and the moment the pore pressure sensors start reading are not unusual.

The signals from the soil moisture sensors are presented in Figure 7-9. In some cases, signal decreases are observed probably due to initial cracking/expansion of the blocks. After some time, the signals begin to increase due to block saturation. In other cases, the signals are continuously increasing.



Figure 7-9. Evolution of the soil moisture sensor signals in different sections. The sensor could be at top or at bottom of the block. The best signal in each section has been chosen. 1722 corresponds to section 2, 1008 to section 4, 1299 to section 5, 0820 to section 7, 0480 to section 8 and 0286 to section 9. Some sensors started measuring at 0.45 V and the signal dropped and increased later. This behavior could be due to water uptake during the DAWE and further drying when the water flowed from the sensors to drier bentonite. The sensor in Section 1 remained dry. In any case, it is clear the sensors indicated that the buffer blocks were wetting. The results must be analyzed carefully as the sensors were installed in powder-filled cavities in the blocks.

7.4 Movements

An assessment of the movements of the different components may help to better understand the system behavior as well, especially if there is any asymmetry in the saturation process.

The displacements measured on the plug face were too small to be accurately measured with the installed sensors. The strain gauges on the plug face did measure increasing levels of strain.

The sensors for measuring displacements in Supercontainer have a range of ± 25 mm. This range may be too small when taking into account the installation process. The initial measures in DS-1082-1, DS-1082-4 and DS-1275-4 were more than 20 mm and DS-1275-3 more than 25 mm. If the sensors are out of the range, it is possible the signals are no longer linear with the displacements. This issue can be checked after dismantling and the sensors can be recalibrated if necessary. The displacements measured by sensors DS-1275-2 and DS-1275-4 were contradictory. The measured displacements could be due to movements of the sensors within their original block positions rather than any displacement of the Supercontainer itself.

The sudden rotations indicated by the inclinometers in very early stages could be due to adjustments of the blocks due to swelling once the gap was water filled.

7.5 Strains

No significant or abrupt strains on the Supercontainer were measured. However, such strains were measured only near one end of the structure and signal was recorded from only two of the strain gauges beyond a few days into the test.

The strains measured on the plug complement the measures from the total pressure sensors and from the displacements sensors. Unfortunately, measurable signal was detected only with the strain gauges. The strains are an indirect measure of the pressures against the plug. It is possible to estimate pressure values from the measured strains (Bendito and Pintado, 2014).

8 WIRELESS SYSTEM STATUS

The wireless transmitters were encapsulated in Äspö on October 2013. After installation (Figure 8-1), nodes 3 to 7 were functioning and nodes 1 and 2 were not. Node 1 has a RS-485 cable for sending data to the MP-40 unit, so this node does not have wireless transmission problem. Receivers 2 and 3 were also functioning.



Figure 8-1. Location of wireless transmitters (or nodes) and receivers in MPT experiment (redcolored instruments correspond to those from which signal was lost after DAWE).

Nodes 3 and 4 failed on December 7, 2013 at 22:25, a few hours after filling the gap and the pellets with water. The reason could be due to the difficulty in transmitting wireless signal through water but only the gap was filled with water and the nodes were sending signal for some hours after filling the gap.

Receivers 1 (R-1) and 2 (R-2) were inspected in January 2014 and the conclusions were that relay 1 did not suffer any electrical short, so the problem lies in the receiver/transmitter itself. Receiver 3 (R-3) was working well.

An attempt was made to recover the signal from the nodes by inserting an antenna through the pelletfilling hole (Figure 8-2) on the plug face and connecting it to a new external receiver. Two antenna lengths were checked using two different rods (0.85 and 1.2 m length). No signals were detected. The 1.2 m length antenna was left in place and the hole was resealed. Additionally, two boreholes (200 mm deep and 20 mm diameter were drilled into the rock near the plug face (see Figure 8-2 for locations) and antennas were inserted. These antennas were also connected to the external receiver. Signals were detected with limited success.



Figure 8-2. *Photographic image of plug face showing locations of pellet-filling hole (through which an antenna was inserted) and additional antenna boreholes.*

Nodes 5, 6 and 7 were working and sending signal for 103 days (until 20.03.2014). Node 4 started to send signal on 07.03.2014 but also stopped on 20.03.2014. The signals from the capacitive hygrometers and pore pressure sensors became constant from 7.03.2014 in sections 2, 5 and 7.

Node 2 started providing signal on 29.01.2014 and stopped on 05.02.2014. The displacement sensors DB-0286-1 and DB-0286-2 gave constant signals. Sensor WC-0286-1 provided constant signal. Sensor WC-0286-2 may be malfunctioning.

The fuse of the MP-40 failed on 20.03.2014. The fuse was changed but the unit was not functioning correctly. It was sent to Aitemin and returned to Äspö after repairs. However, no signal is currently being recorded. The reasons for this malfunctioning are not evident. The battery capacity should be sufficient because the transmission frequency was 12 hours and the battery duration should be four years at this frequency. R-3 was working but is now disconnected due to short-circuiting.

9 CONCLUSIONS

The total pressure sensors in the rock, the pore pressure sensors in the rock, the capacitive hygrometers, the psychrometers and the soil moisture sensors appear to be functioning adequately.

The total pressure sensors in the rock are measuring some hundreds of kPa and their signal evolution is similar to that of the pore pressure sensors in rock suggesting that these sensors are not measuring bentonite swelling pressure except in section one, where the sensors are closer to the blocks and are in contact with the bentonite, measuring swelling pressure as well.

There are no significant differences between distance blocks, blocks inside the Supercontainer and blocks in transition zone both in terms of the total pressure development in the rock and in the saturation process measured by the capacitive hygrometers, psychrometers and soil moisture sensors. The only differences are due to the position of the saturation sensors inside the blocks: the closer sensor is to the gap the faster is the saturation process (as expected). Some unexpected rapid saturation recorded by a few of the sensors at the beginning of the test could be explained by to the presence of cracks or damage in the blocks leading to direct contact between the sensors inside the blocks with the gap. This contact was then lost when the bentonite swelled, thus sealing the different flow paths.

There are clear differences in the evolution of the total pressure measurements when comparing the pellet filling and the bentonite blocks. This is attributed to the different behavior of the pellet filling when swelling.

The pore pressure sensors in the buffer are not measuring positive pressures yet. This is due to the long time necessary for filling all the experiment gaps with water, including the bentonite pores and the sensor cavities. The bentonite has an extremely low hydraulic conductivity and the saturation of the pores and sensor cavities will likely require some years.

The sensors for measuring movements in the blocks and in the Supercontainer have provided some information but due to complexity of the potential movements of KBS-3H components, it is difficult to analyze the data. The installation of the KBS-3H components is quite complex and the sensors could remain over-ranged after the installation. The installation of higher range sensors could avoid this problem in future tests.

The strain gauges are a novel sensor for "in situ" tests in nuclear waste management. They can provide useful information from the early stages of the test but it is clear that the corrosion of the plug and the saturation process in the Supercontainer will be problematic for using these sensors in long term tests if they cannot be properly protected.

The extensioneters in the plug have not measured any displacement yet because the inner total pressure is still very low. Extensioneters with lower ranges in parallel with higher range sensors could be useful. In this case, a deep study about the displacements expected in the plug should have been done before the dimensioning of the test. The tool proposed in the next chapter for plug pressure calculation could be useful in the future.

The wireless system was working as intended at the very beginning of the test. Although the transmitters were properly encapsulated and their batteries calculated to run for 4 years at a measuring interval of 12 hours, most signals were lost during the early stages of the test. The potential advantages offered by this kind of system justify the attempt made.

The main conclusion gathered is that higher redundancy is needed. For instance, by including additional receivers or even just antennas connected to redundant receivers. In this sense, the existing memory card inside the transmitters for saving the data could provide part of the data lost when dismantling the test.

For future experiments, transmitter operation could be improved if they collect signals over certain periods of time and send them once per week or per month, thus decreasing the battery consumption and therefore extending their life. As the measuring frequency of the transmitters can be remotely changed, the best approach could be to set a relatively high frequency (every 10 minutes for example) for adjusting and measuring at the early stages and then change to a lower frequency in order to preserve the duration of the battery. If the transmitter does not receive any order from the receivers during a certain period of time (one day for example), the measuring period could be increased to 12-24 hours automatically.

10 FUTURE ACTIONS

The gas pressure sensors in the gap have a range of 250 kPa. In order to be able to measure the pore pressure in gap and to discriminate the swelling pressure from the water pressure, the sensors will be changed to others with higher range.

The datalogging system will be reviewed. There are some sensors which are not reading and others with strange behavior that should be checked, for instance, it could be possible to recover the total pressure sensors in blocks (the ones manufactured by ÅF/Geokon).

The sensors measuring displacements on the plug face could be changed to those with lower range.

The pressures measured in the boreholes of section 9 should be compared with pressures measured separately in other boreholes close to the drift if such data exists. It should be taken into account that the boreholes in section 9 are close to a drain (i.e., the drift) and it is possible that these pressures may not follow the water pressure evolution of other boreholes which lie farther away.

The strain gauge data could be used to estimate the inner pressure on the plug face (Figures 10-1 and 10-2). It is necessary to develop a computational tool for performing such estimates but this tool can be used for future analysis.



Figure 10-1. Plug discretization.



Figure 10-2. Detailed mesh.

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